



# The NGA-East Ground Motion Characterization (GMC) Model



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*Technical Integration Lead*

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G. Atkinson, R. Graves, N. Abrahamson  
Y. Bozorgnia

And contributions from many more...

<http://peer.berkeley.edu/ngaeast/>

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# The NGA-East Project

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*A science/development phase  
AND a SSHAC Level 3 project*

Objective – to develop GMC model:

- GMMs/GMPEs
  - Median
  - Standard Deviation (aleatory variability)
- Logic trees (epistemic uncertainty)

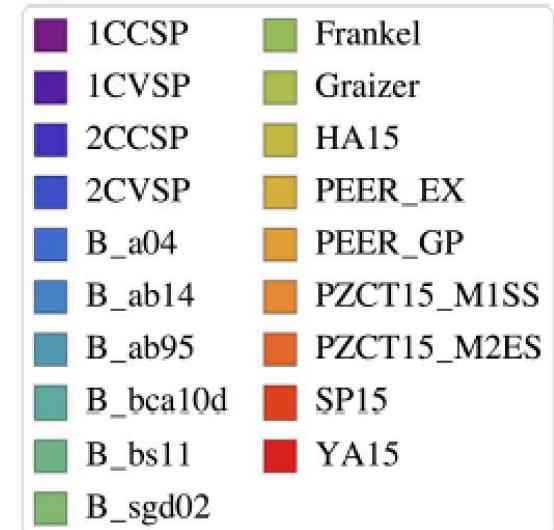
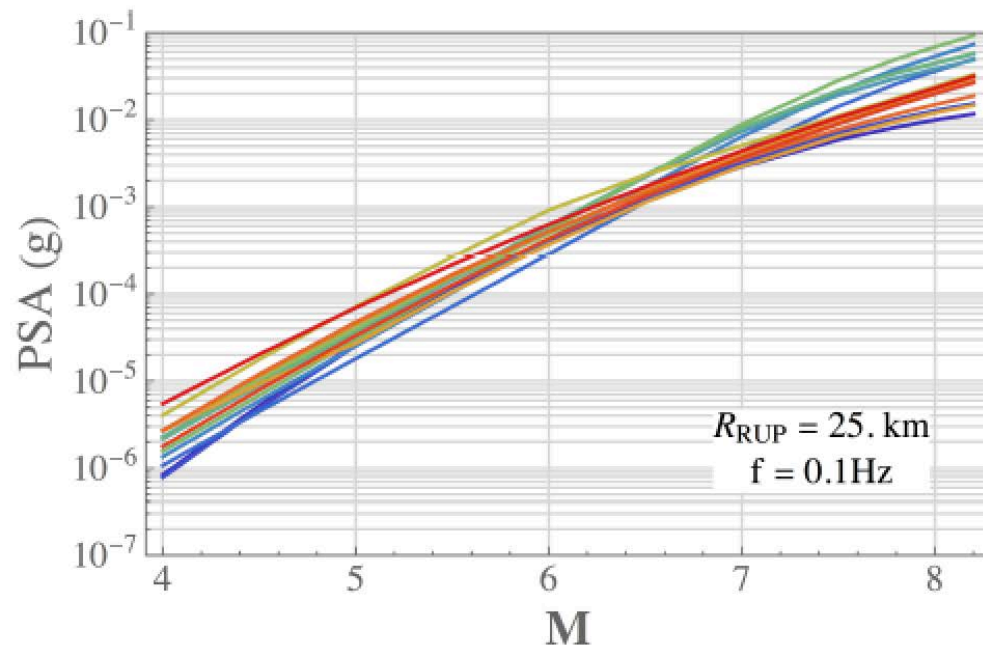
## **SSHAC Goals:**

**Evaluation:** The consideration of the complete set of data, models, and methods proposed by the larger technical community that are relevant to the hazard analysis.

**Integration:** Representing the center, body, and range of technically defensible interpretations in light of the evaluation process (**CBR of the TDIs**).

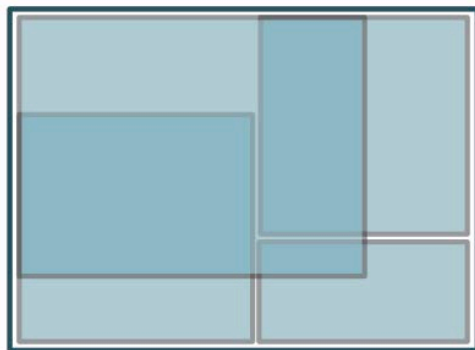
# Capturing the CBR of the TDI in median ground motions

- Issue: many GMMs exist, but they may not sample the ground-motion space adequately
  - Redundant models? Confirmatory models?
  - Missing models?

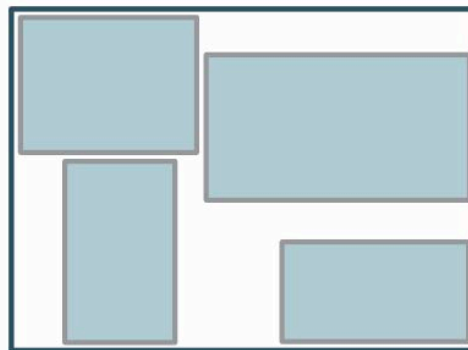


# Capturing the CBR of the TDI in median ground motions

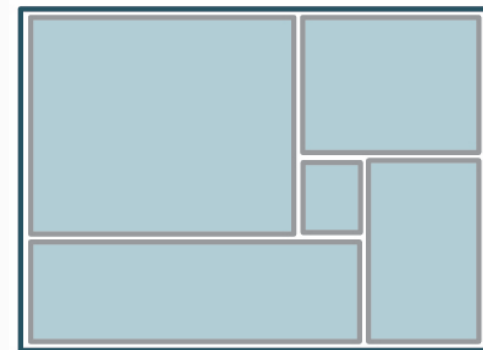
- Issue: many GMMs exist, but they may not sample the ground-motion space adequately
  - Redundant models? Confirmatory models?
  - Missing models?
- NGA-East approach: treat epistemic uncertainty as a continuous distribution in GM space
  - Goal is to *try to* select discrete mutually exclusive and completely exhaustive (MECE) GMMs representing the range in ground motions



NOT  
mutually exclusive



NOT  
completely exhaustive



**MECE**

# Capturing the CBR of the TDI in median ground motions

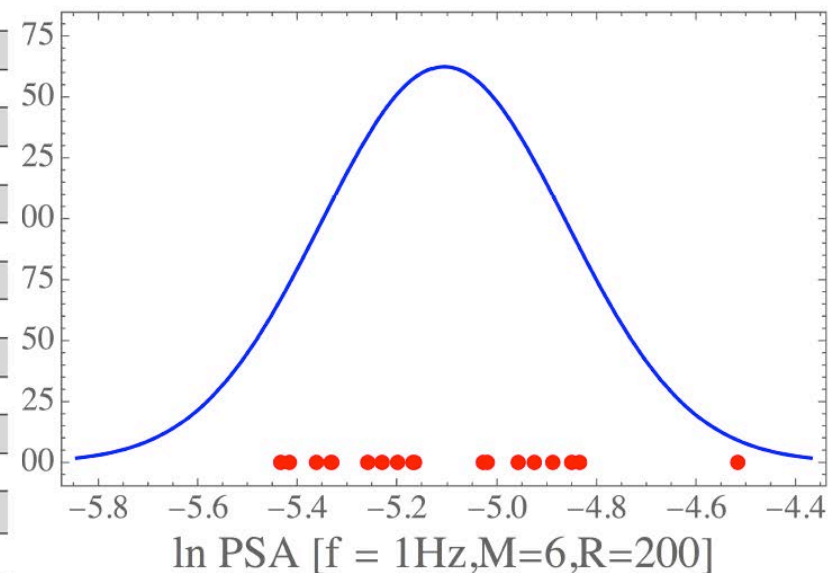
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- Issue: many GMMs exist, but they may not sample the ground-motion space adequately
  - Redundant models?
  - Missing models?
- NGA-East approach: treat epistemic uncertainty as a continuous distribution in GM space
  - Goal is to *try to* select discrete mutually exclusive and completely exhaustive (MECE) GMMs representing the range in ground motions
- Need to further populate the ground-motion space before re-discretizing into a manageable number of GMMs

# 1D example (M6, R200)

1. Seed models evaluated and selected, left with 18 values (table)
2. Develop model based on distribution (mean, std dev)

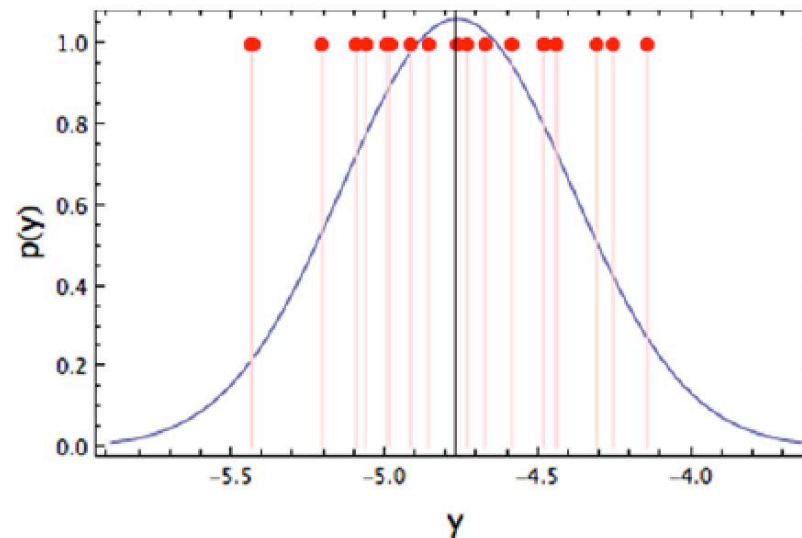
Model Number	ln PSA(1Hz,M=6,R=200)
1	-4.517
2	-4.834
3	-5.258
4	-5.433
5	-4.926
6	-5.164
7	-4.850
8	-5.362
9	-5.020
10	-5.230
11	-5.332
12	-5.331
13	-5.028
14	-5.416
15	-4.888
16	-4.958
17	-5.167
18	-5.198



# 1D illustration of process

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- 1. Develop a suite of seed ground-motion models (GMMs)
- 2. Develop parameters for continuous distributions of GMMs (mean and standard deviation)
- 3. Visualize the ground-motion space (trivial in 1D)

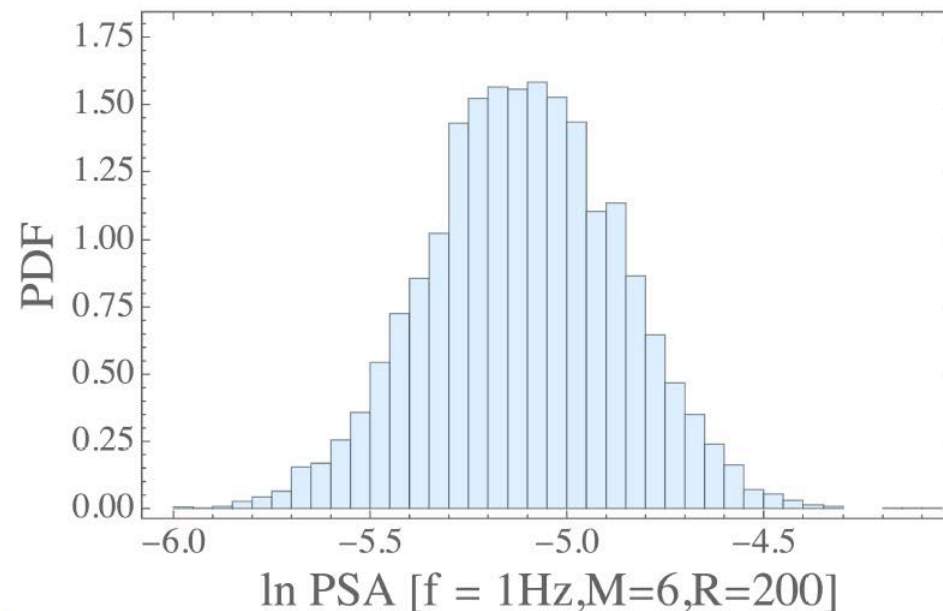




# 1D illustration of process

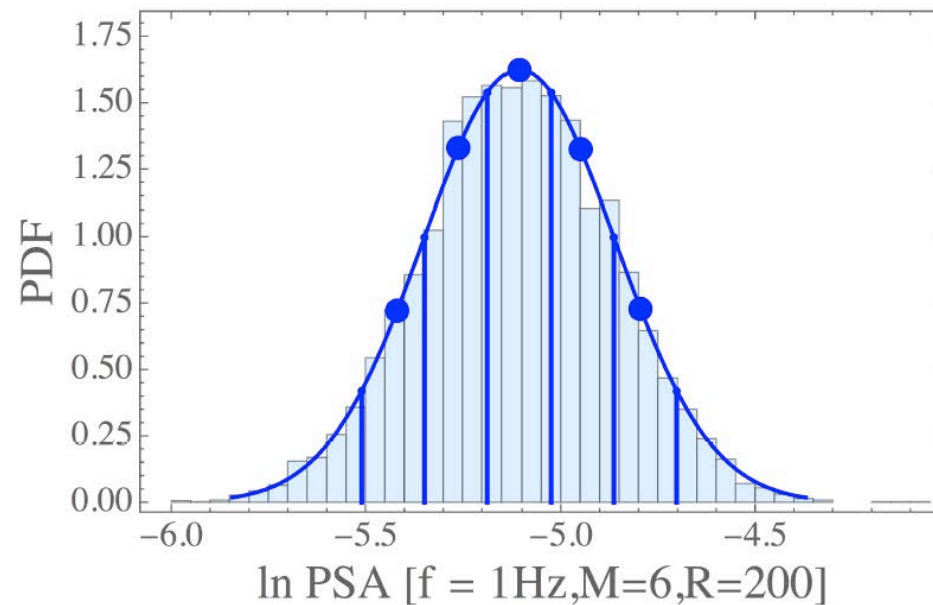
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- 1. Develop a suite of seed ground-motion models (GMMs)
- 2. Develop parameters for continuous distributions of GMMs
- 3. Visualize the ground-motion space and sample GMMs



# 1D illustration of process

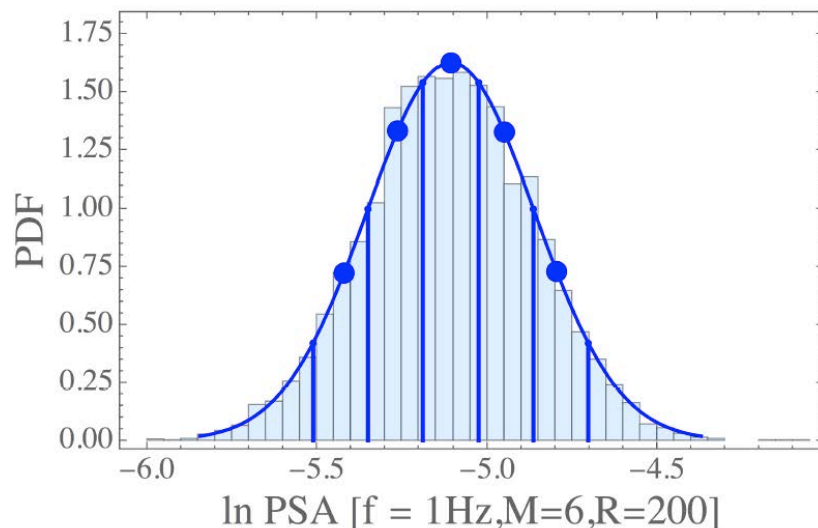
- 1. Develop a suite of seed ground-motion models (GMMs)
- 2. Develop parameters for continuous distributions of GMMs
- 3. Visualize the ground-motion space and sample GMMs
- 4. Re-discretize the ground-motion space, select representative models



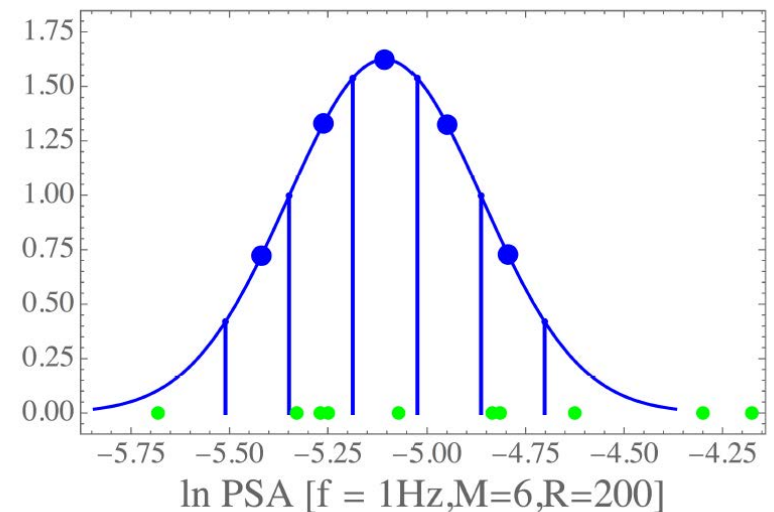
# 1D illustration of process

- 1. Develop a suite of seed ground-motion models (GMMs)
- 2. Develop parameters for continuous distributions of GMMs
- 3. Visualize the ground-motion space and sample GMMs
- 4. Re-discretize the ground-motion space
- 5. Assign weights

Based on sampled distribution

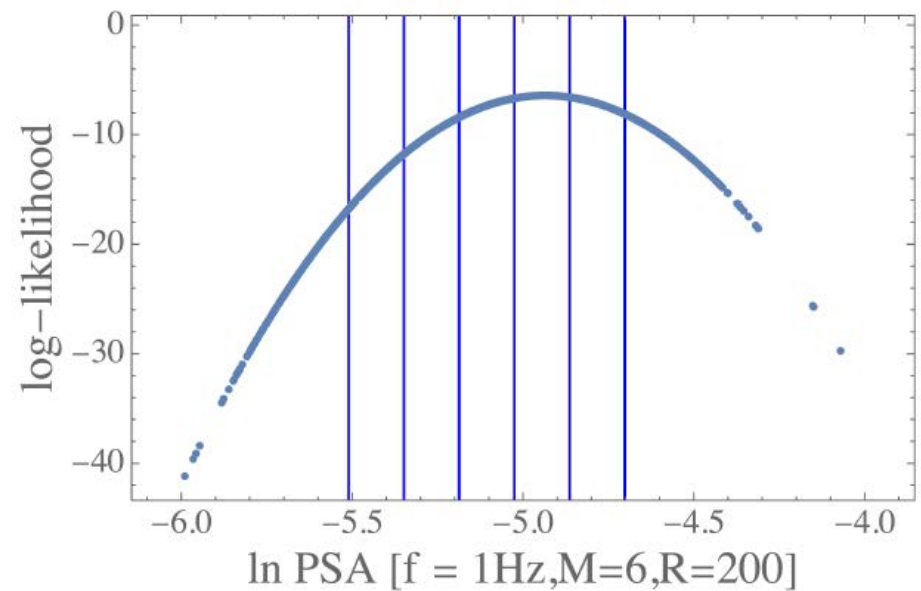
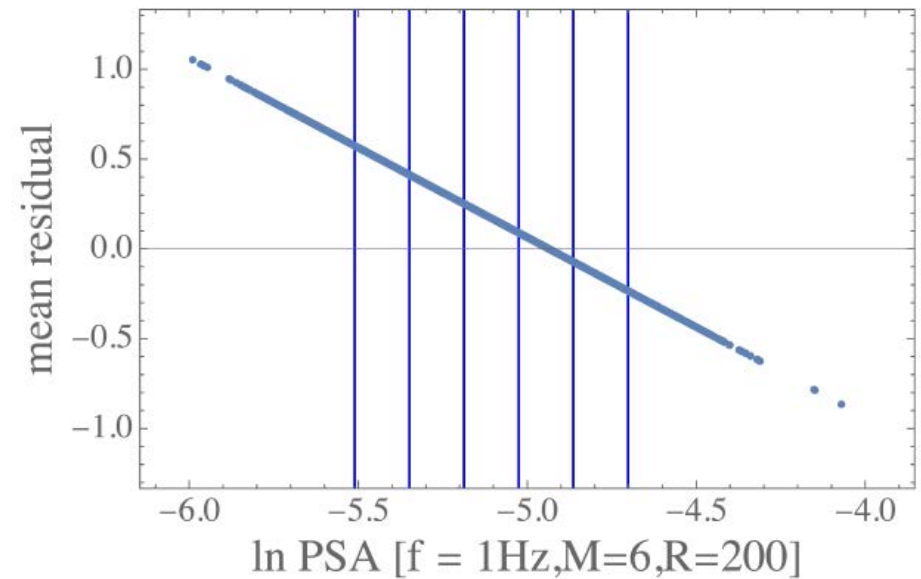
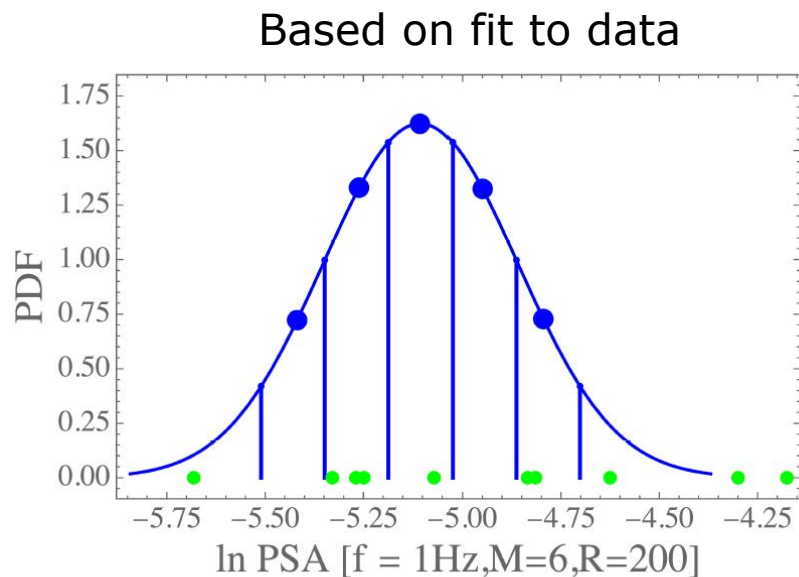


Based on fit to data



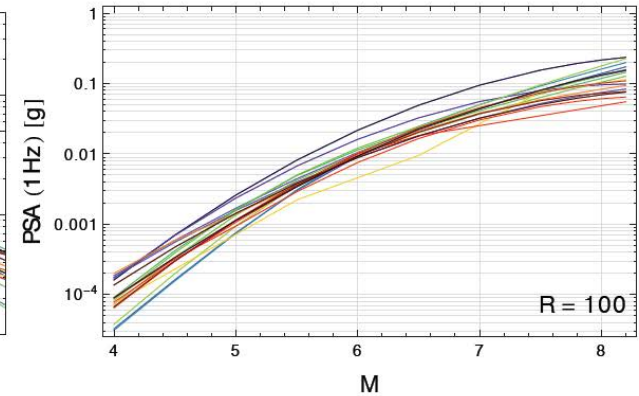
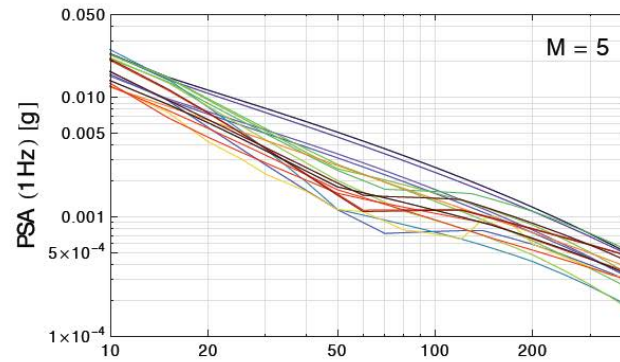
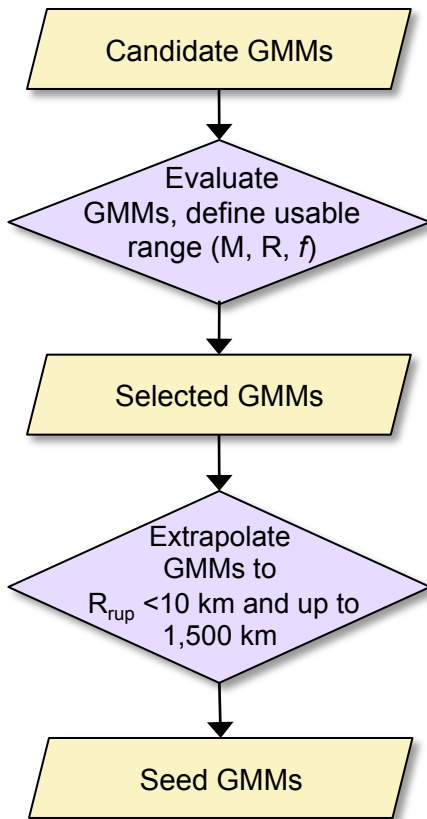
# 1D illustration of process

- 5. Assign weights

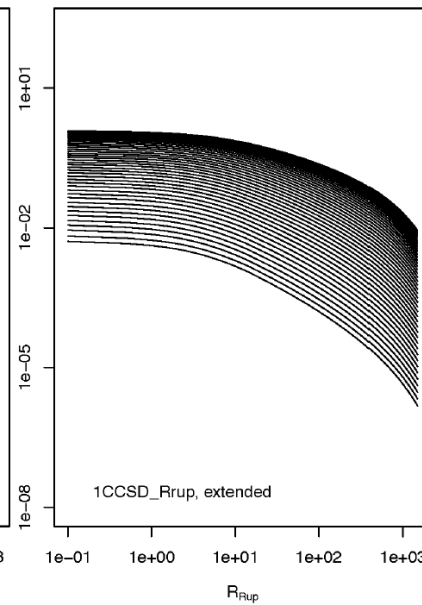
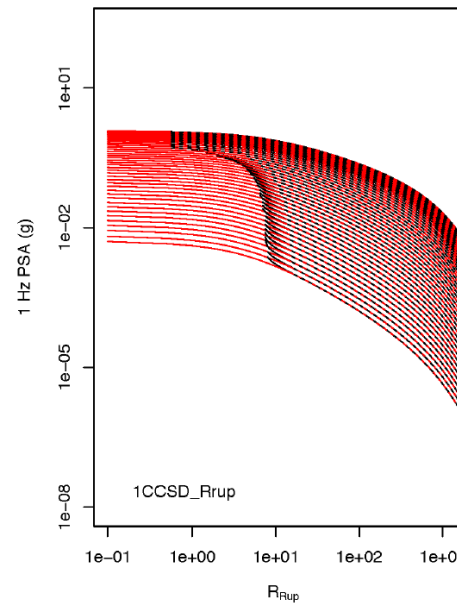


# Median ground motions

## 1. Develop set of seed GMMs



- 1CCSD ■ 1CVSD ■ 2CCSD ■ 2CVSD ■ B\_a04 ■ B\_ab14 ■ B\_ab95
- B\_bca10d ■ B\_bs11 ■ B\_sgd02 ■ Frankel ■ Graizer ■ HA15
- PEER\_GP ■ PZCT15\_M1SS ■ PZCT15\_M2ES ■ SP15 ■ YA15



## New Candidate Model Developers (10 groups)

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- D.M. Boore
- R.B. Darragh, N.A. Abrahamson, W.J. Silva, and N. Gregor
- E. Yenier and G.M. Atkinson
- S. Pezeshk, A. Zandieh, K.W. Campbell, and B. Tavakoli
- A. Frankel
- A. Shahjouei and S. Pezeshk
- M.N. Al Noman and C.H. Cramer
- V. Graizer
- B. Hassani and G.M. Atkinson
- J. Hollenback, N. Kuehn, C.A. Goulet and N.A. Abrahamson

**PEER Reports  
No. 2015/04  
and 2015/08**

# Legacy Median Candidate GMMs

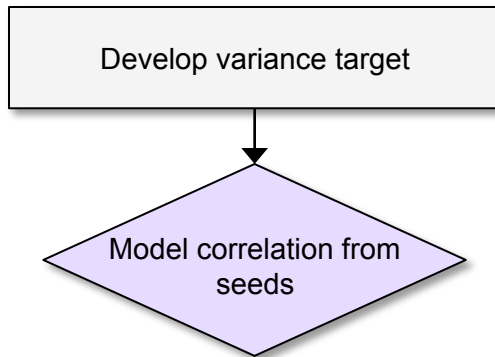
## EPRI 2013 Review Project GMMs

Model	Name and year	Included	Comments
*A08p	Atkinson (2008, 2011)	No	Superseded
*AB06p	Atkinson and Boore (2006, 2011)	No	Superseded
*FEL	Frankel (1996)	No	Superseded
**PZT	Pezeshk, Zandieh and Tavakoli (2011)	No	Superseded
**SDCS	Silva et al. (2003), double corner	No	Superseded
*SEL01NR	Somerville et al (2001), non-rift	No	Expired, poor fit below M5, limited period range
*SEL01R	Somerville et al (2001), rift	No	Expired, poor fit below M5, limited period range
**SSCCSS	Silva et al. (2003), single corner constant stress	No	Superseded
**SSCVS	Silva et al. (2003), single corner variable stress	No	Superseded
*TEL	Toro et al. (1997), middle continent	No	Superseded

\* 2014 NSHMP, \*\* 2014 NSHMP used earlier version

# Median ground motions

## 2. Develop continuous distribution of GMMs

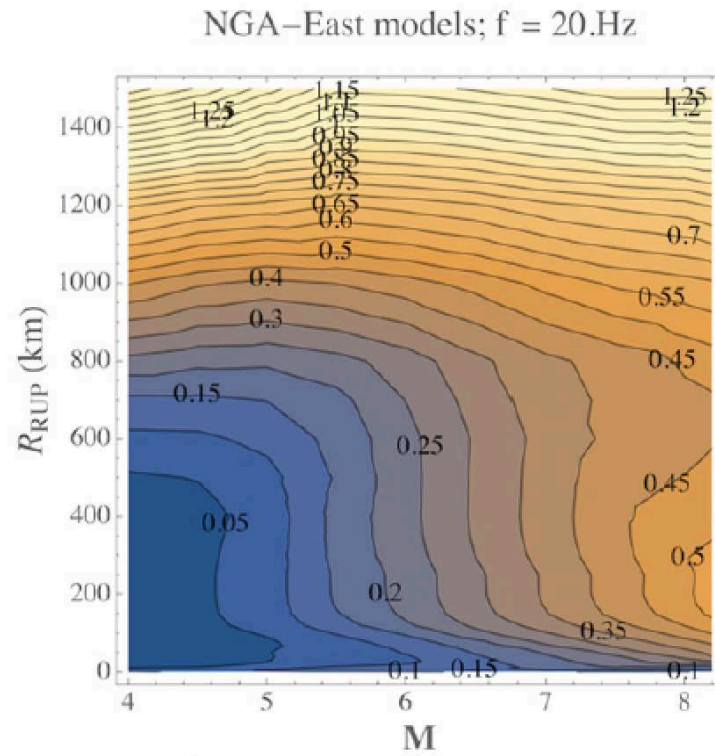
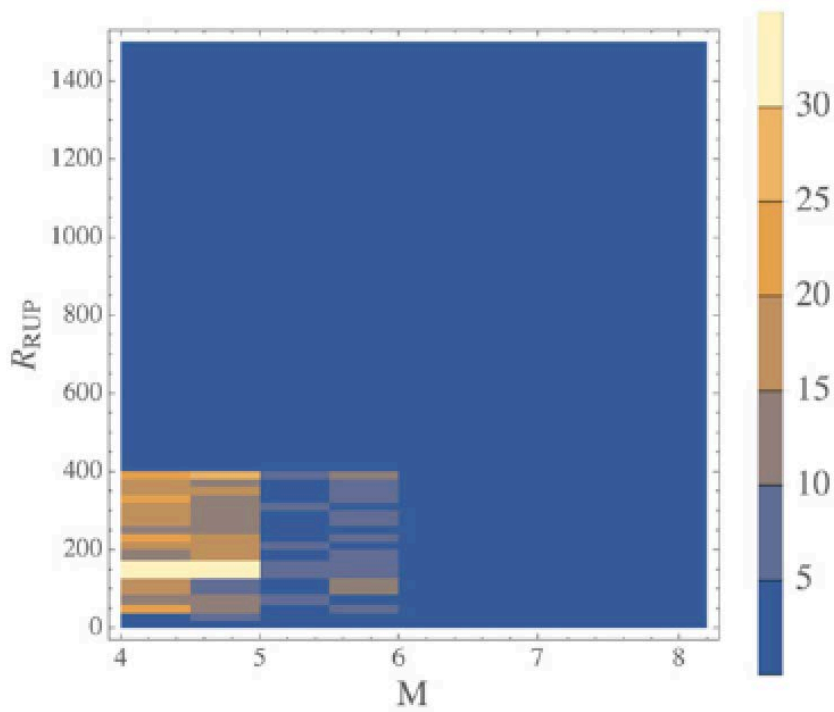


### Critical step:

It defines width of distribution in terms of variance = epistemic uncertainty coverage

### Considerations:

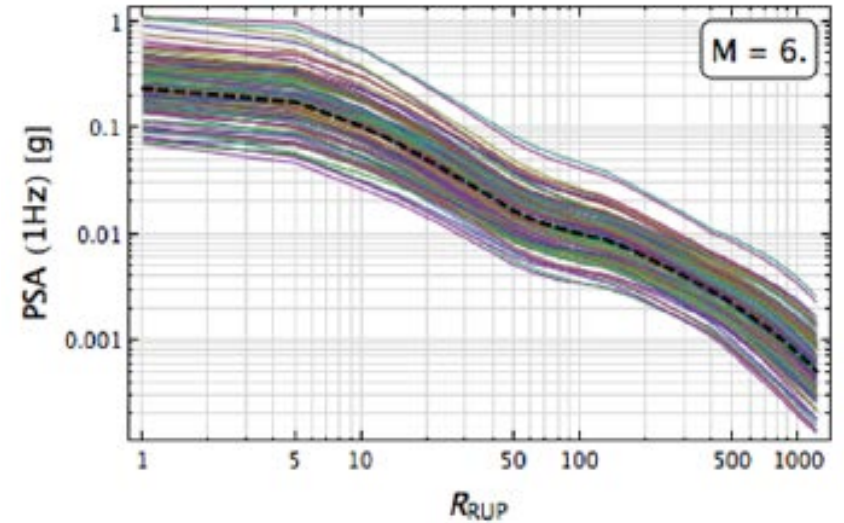
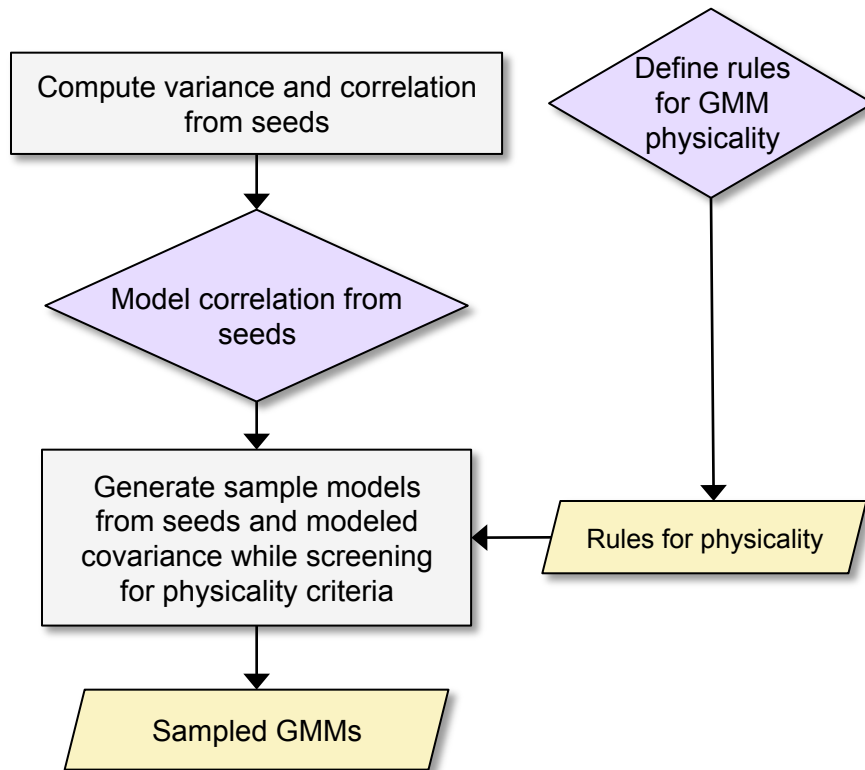
1. Should be lowest where there is data and increase beyond data range
2. Should be larger than WUS





# Median ground motions

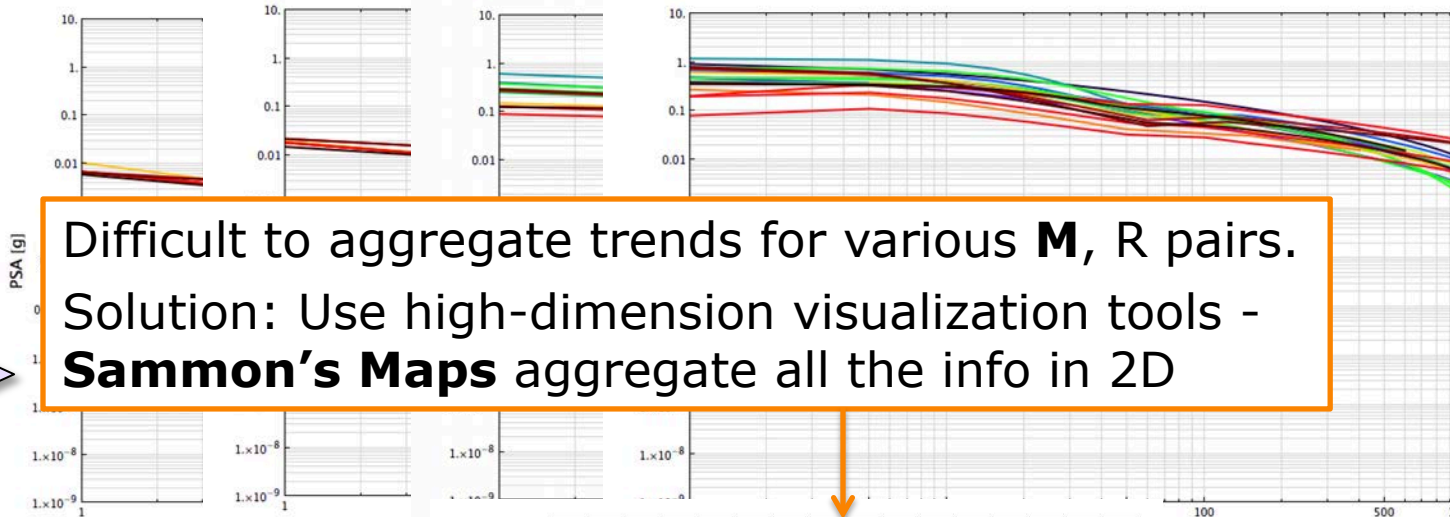
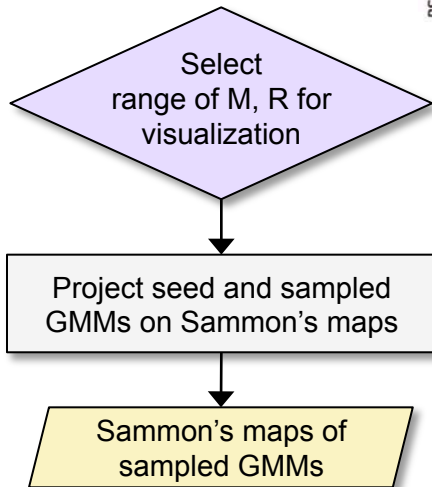
## 2. Develop continuous distribution of GMMs



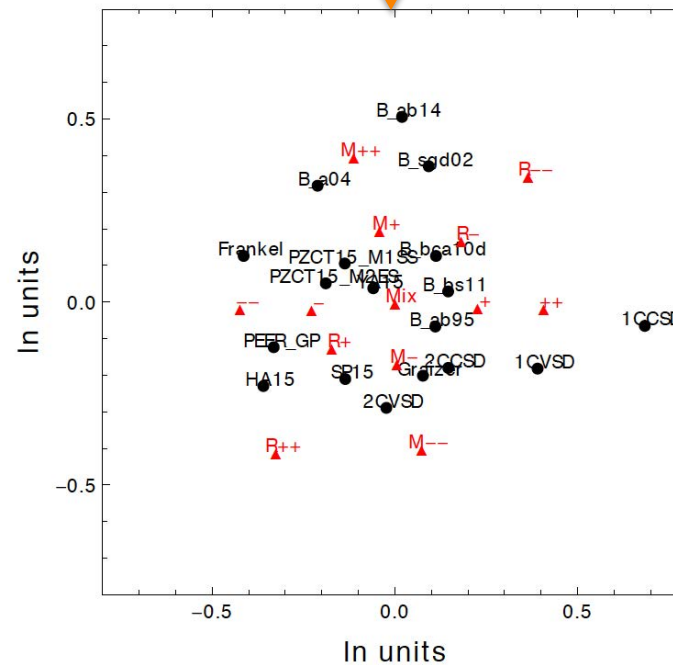
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# Median ground motions

3. Visualize the GM space



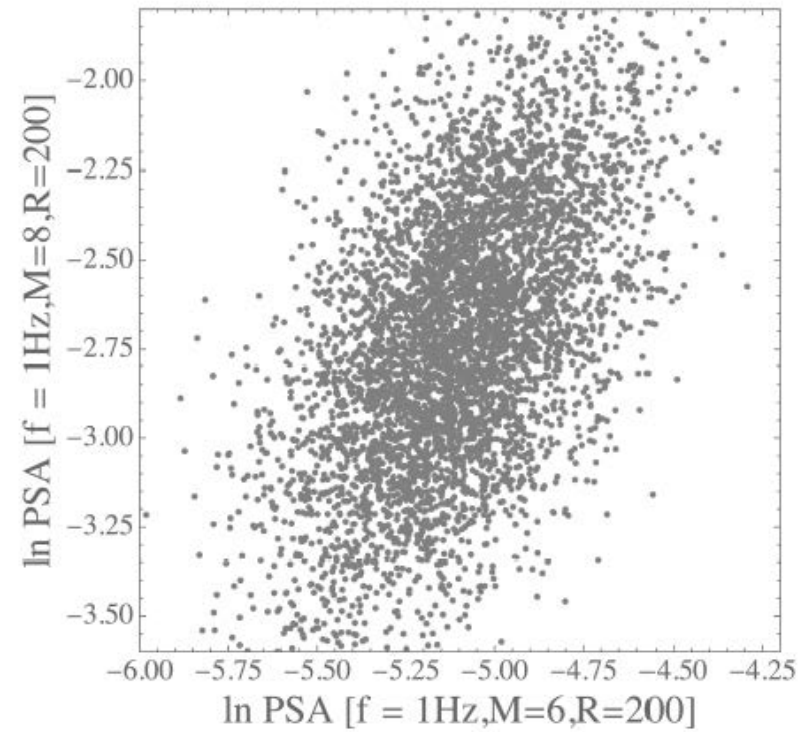
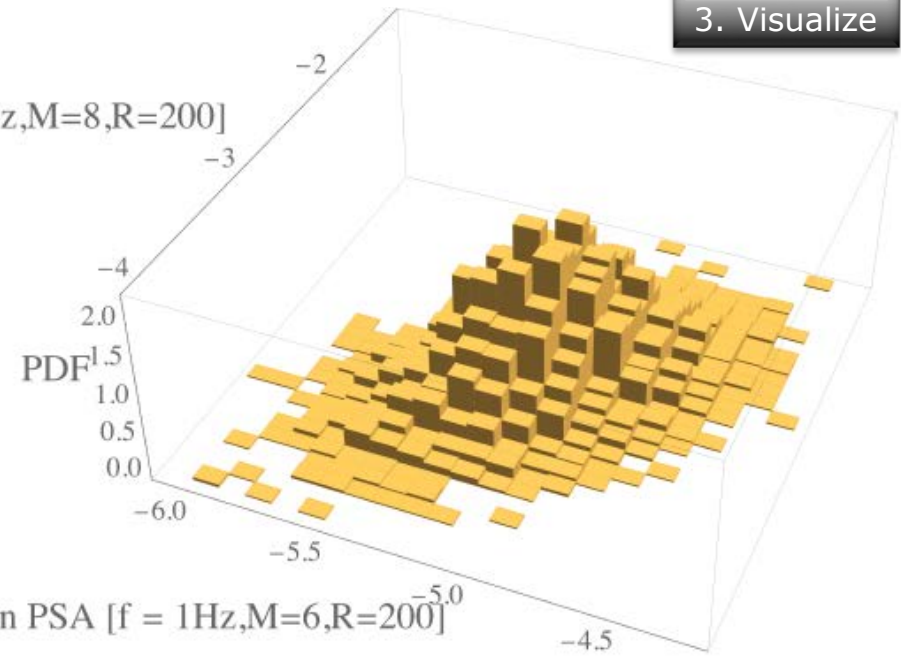
Difficult to aggregate trends for various **M**, **R** pairs. Solution: Use high-dimension visualization tools - **Sammon's Maps** aggregate all the info in 2D



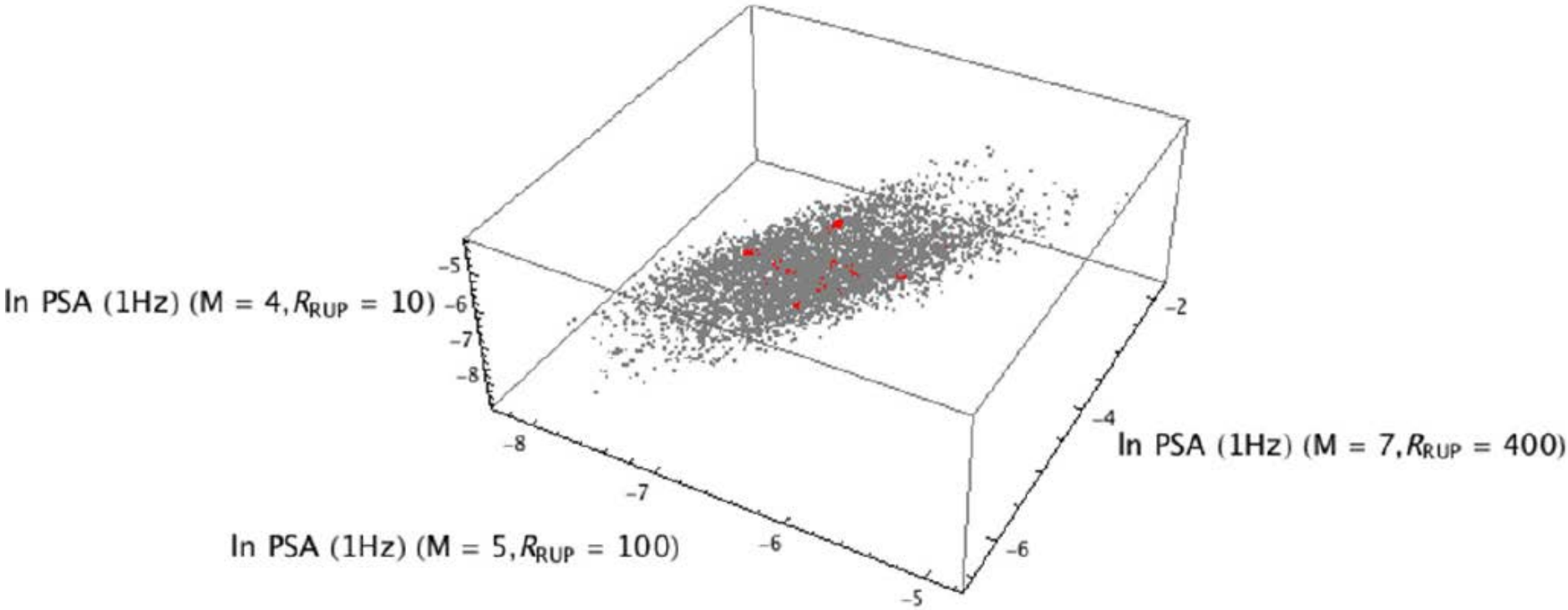
# 2D case

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$\ln \text{PSA} [f = 1\text{Hz}, M=8, R=200]$

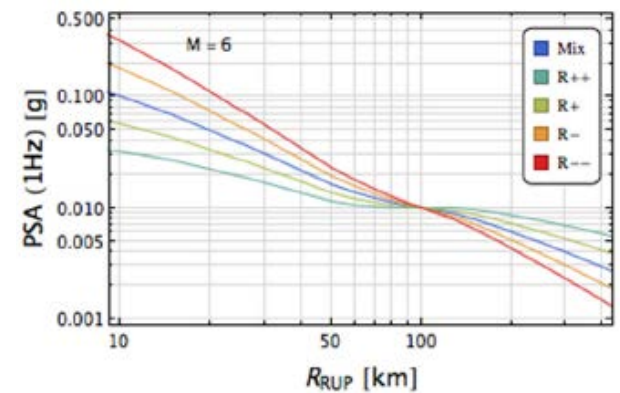
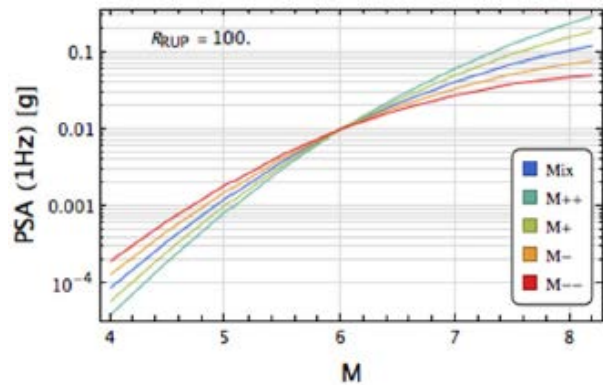
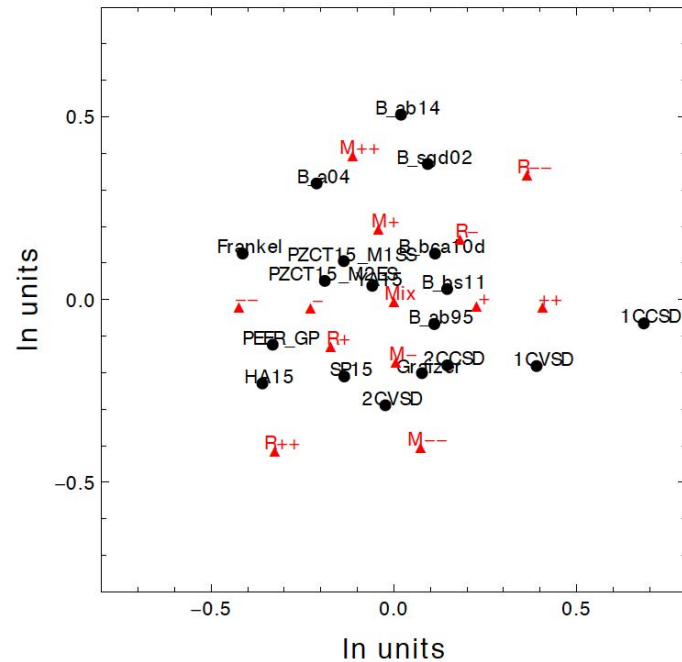
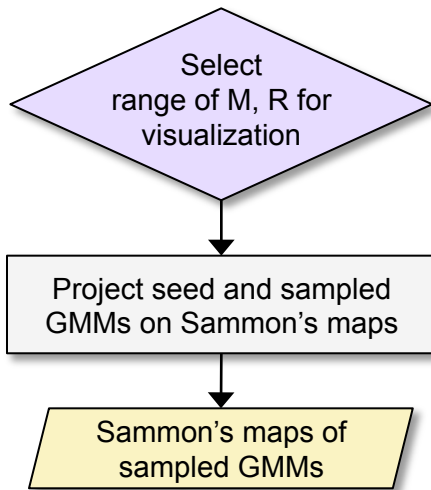


# 3D case produces a thin cloud



# Median ground motions

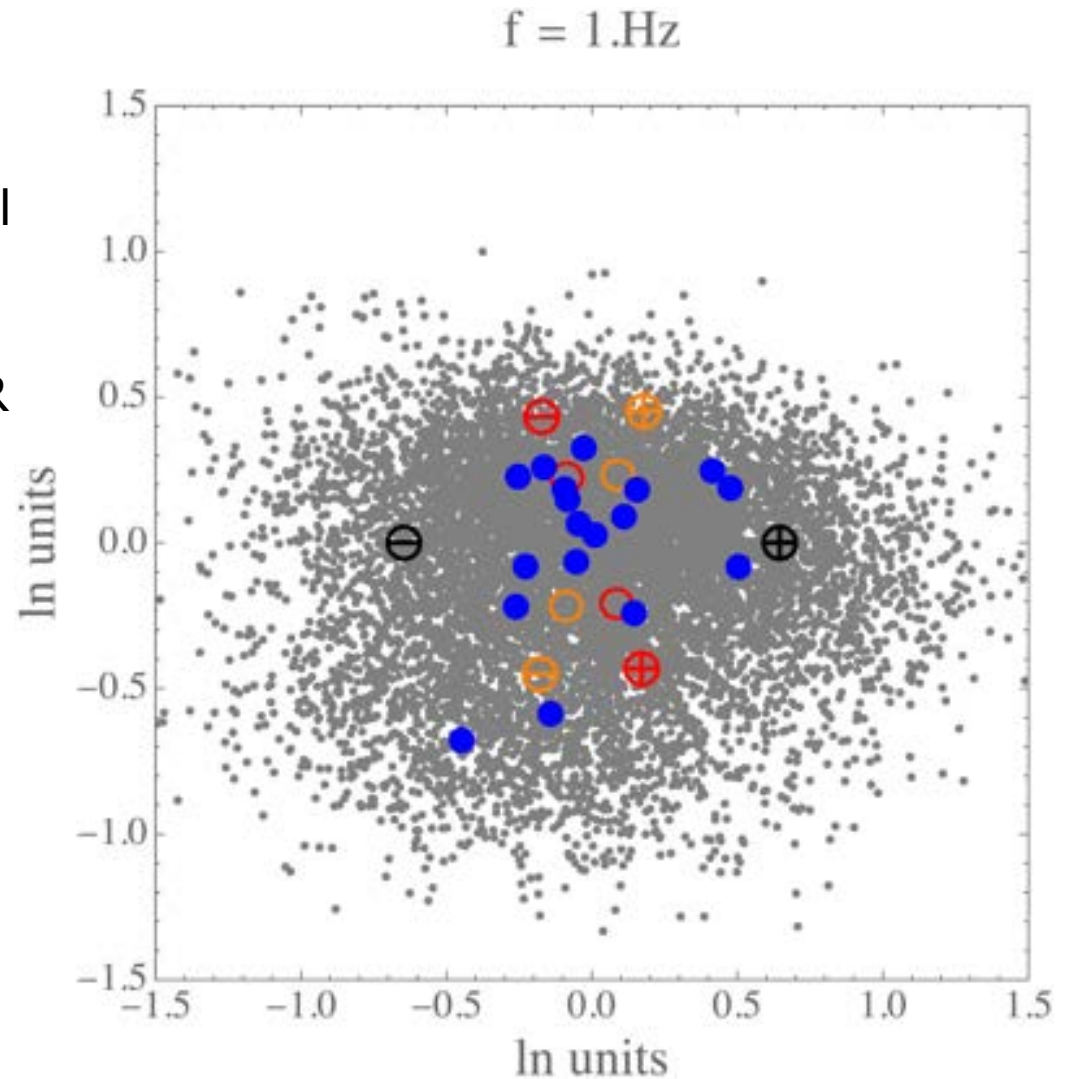
## 3. Visualize the GM space



# Median Ground Motions

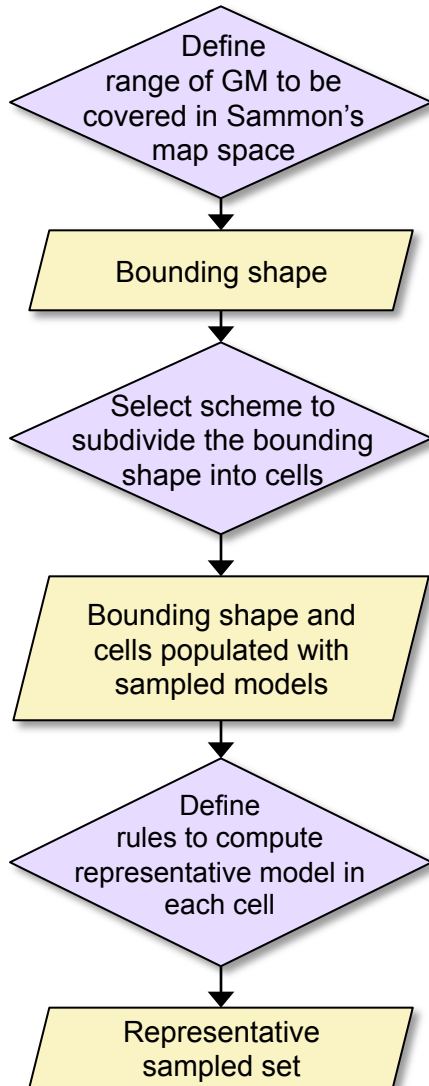
## 3. Visualize the GM space

- Combine the variance model and correlation models from the seeds.
- Populate GM-space with M,R scenarios:  $M=4-8.2$  &  $R=0-1500$  km
- Each resulting GMM is a vector of ground-motion values
- Project seeds and samples on Sammon's map

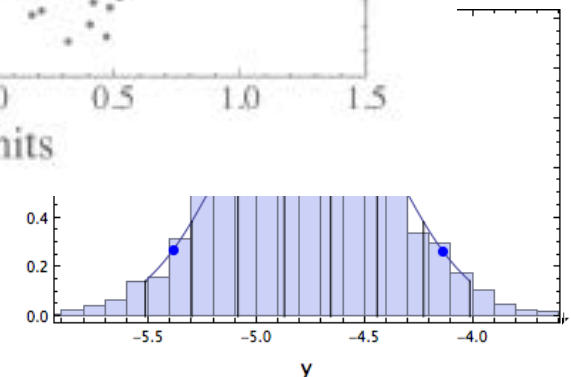
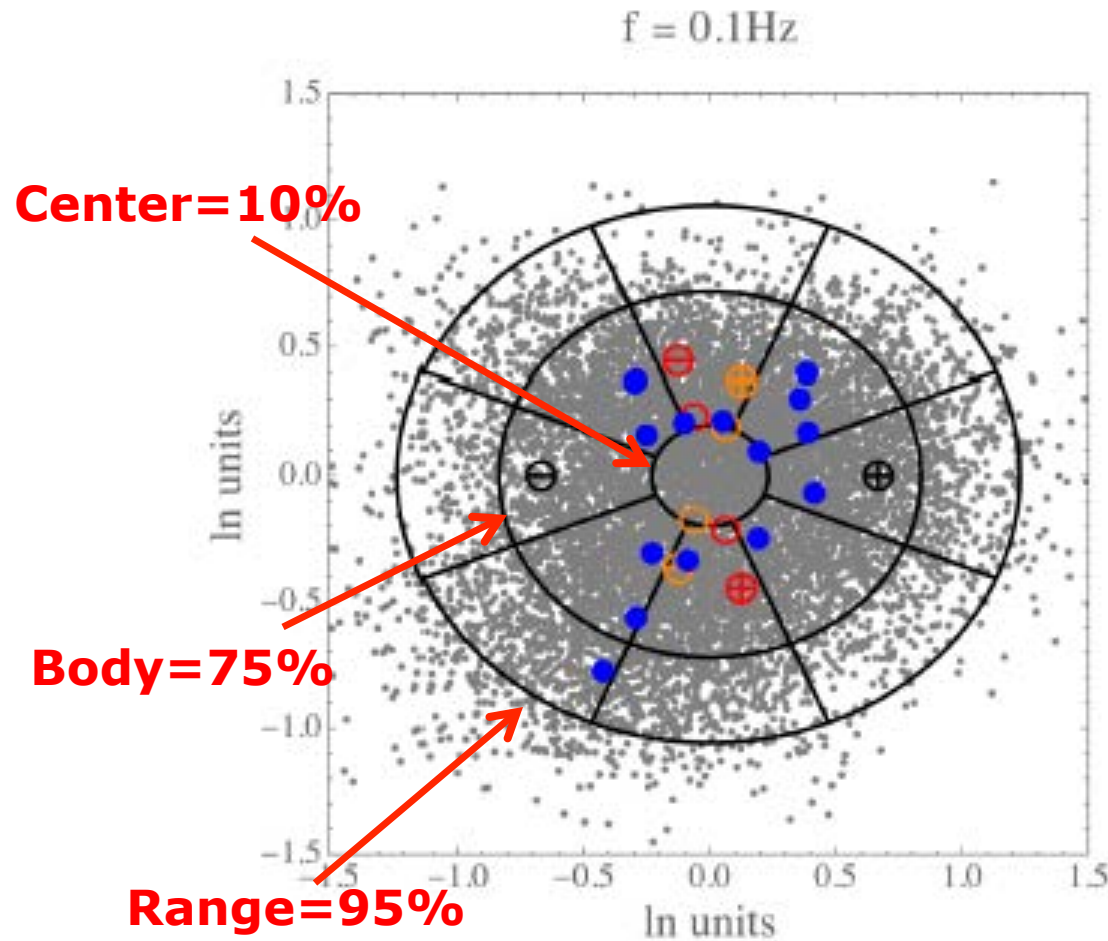


# Median Ground Motions

## 4. Discretize the GM space

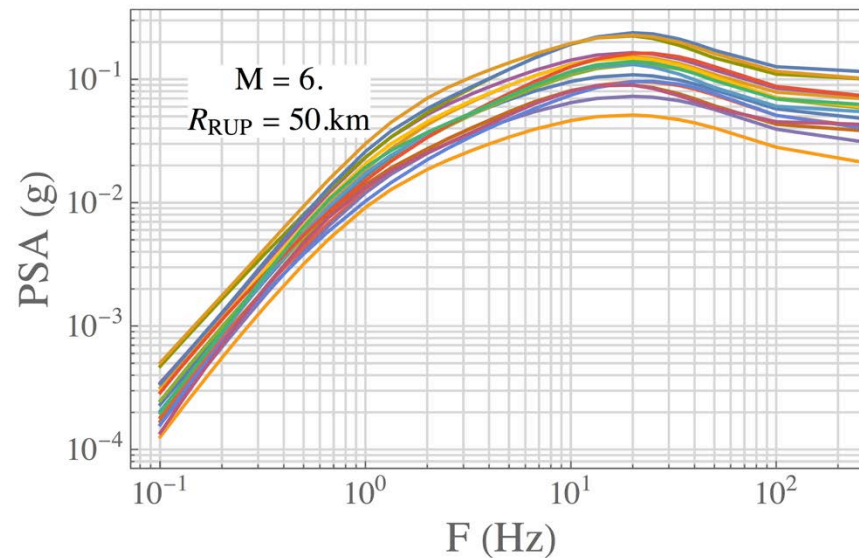
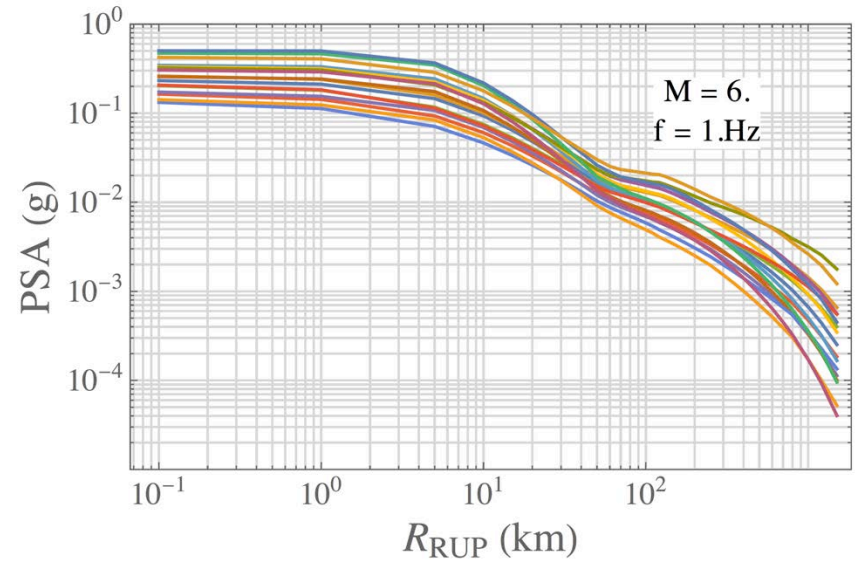
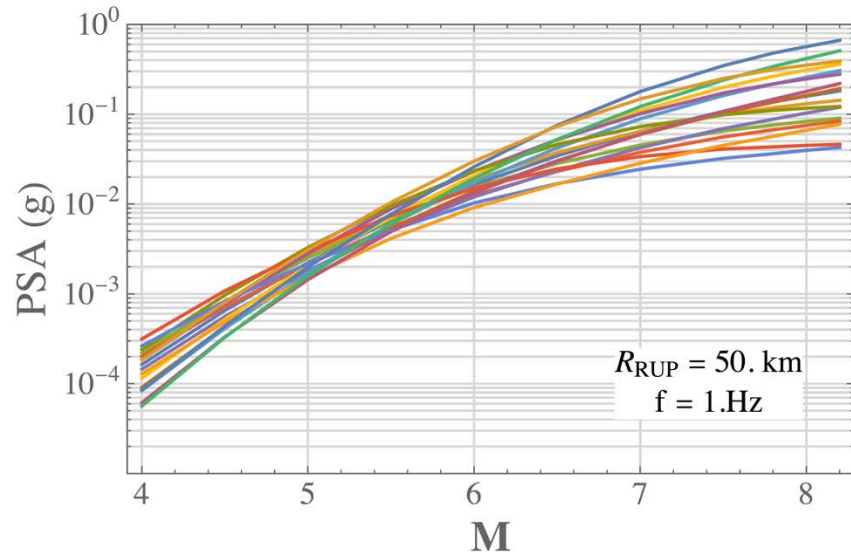


Sample Sammon's map space using ellipse with 17 cells



# Sample result

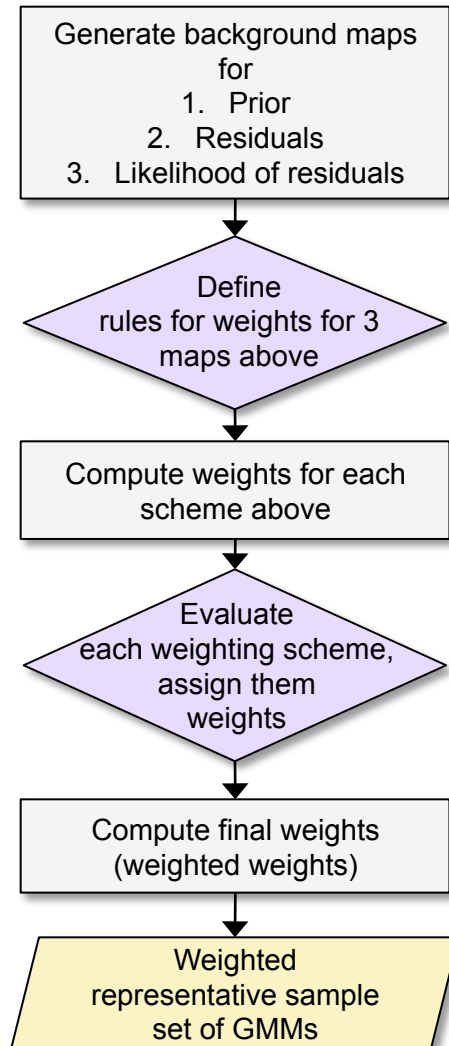
- 17 GMMs, each representing one cell





# Median Ground Motions

## 5. Assign weights

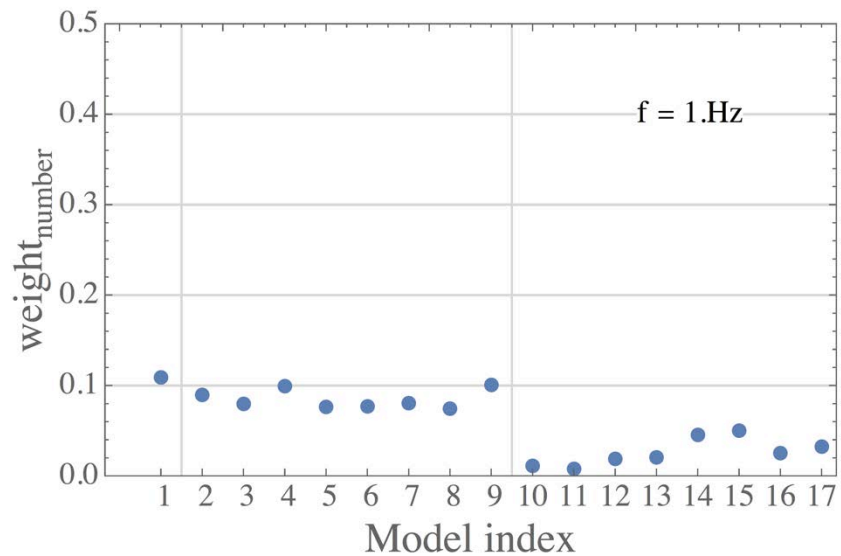
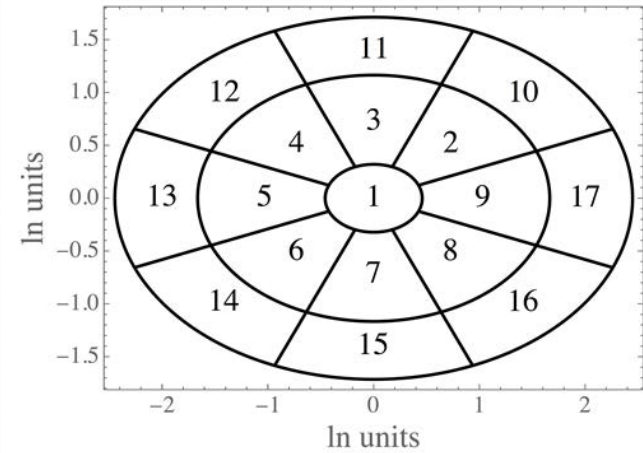
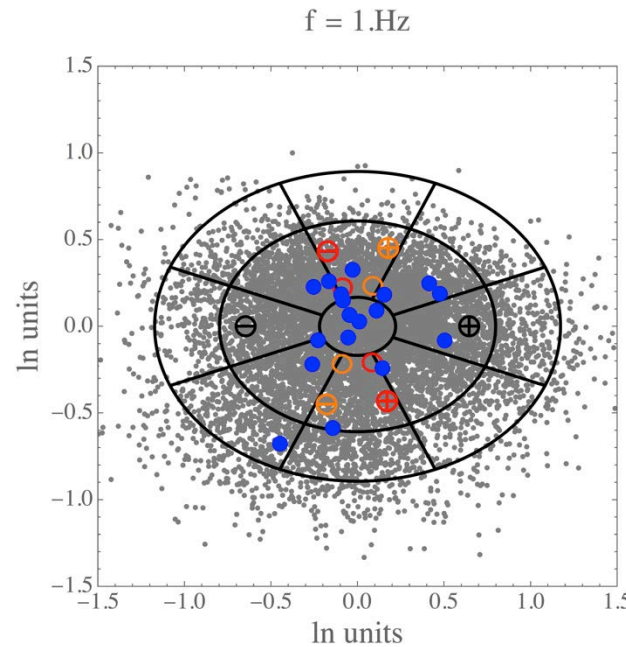
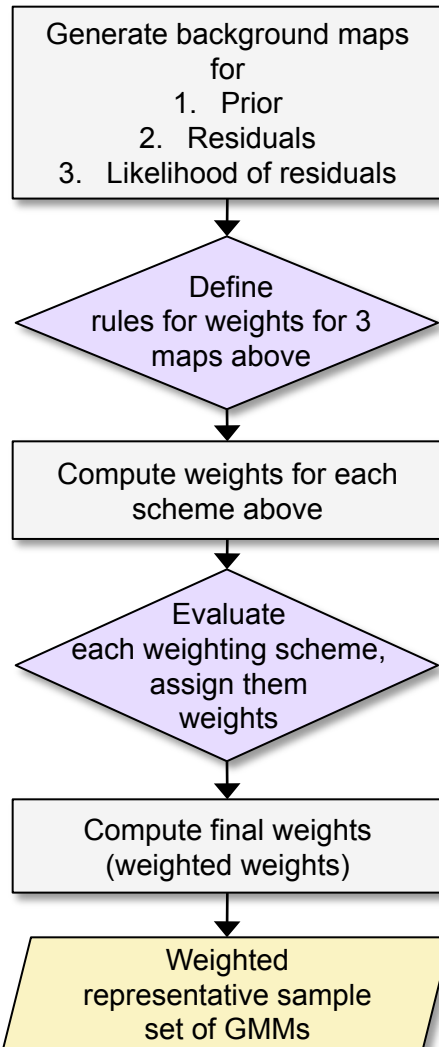


## Weights

- Number of models in cell (Nsamples)
- Residuals (res)
- Likelihood (like)

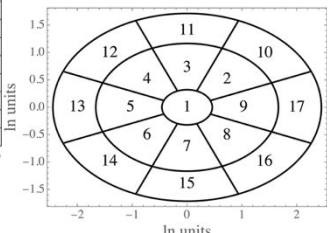
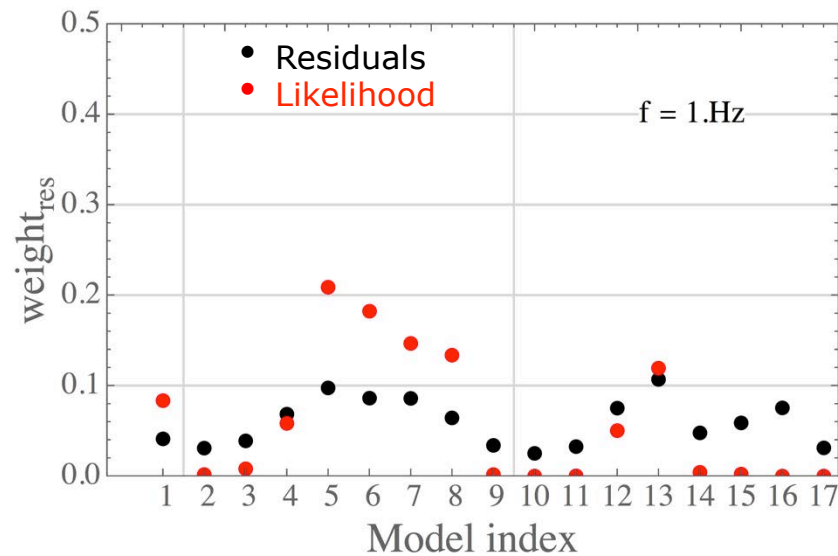
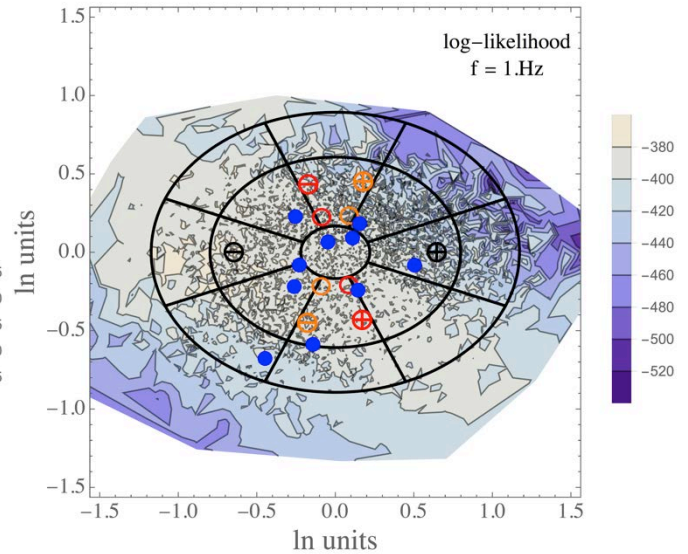
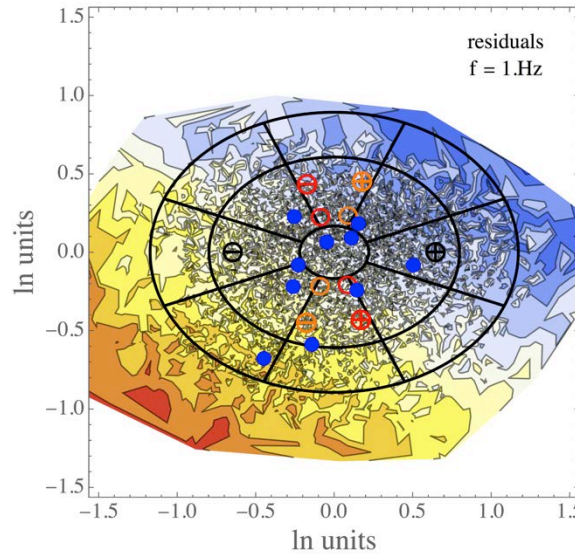
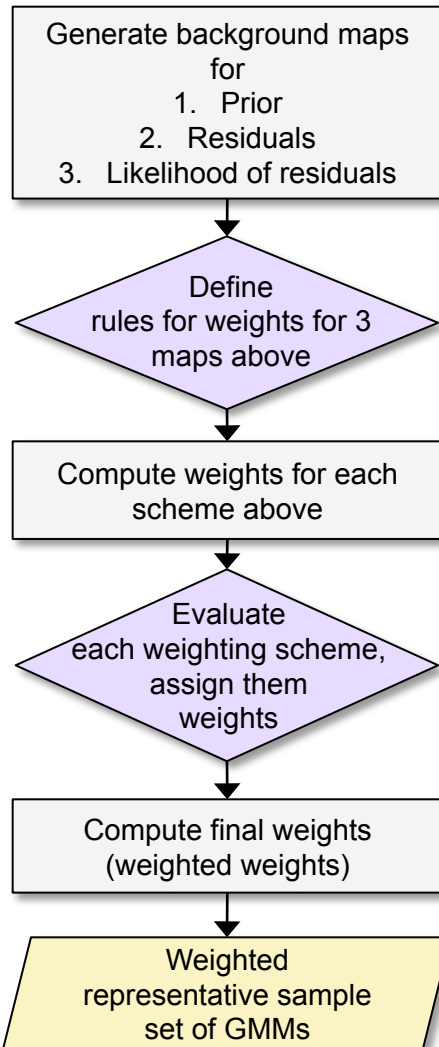
# Median Ground Motions

## 5. Assign weights



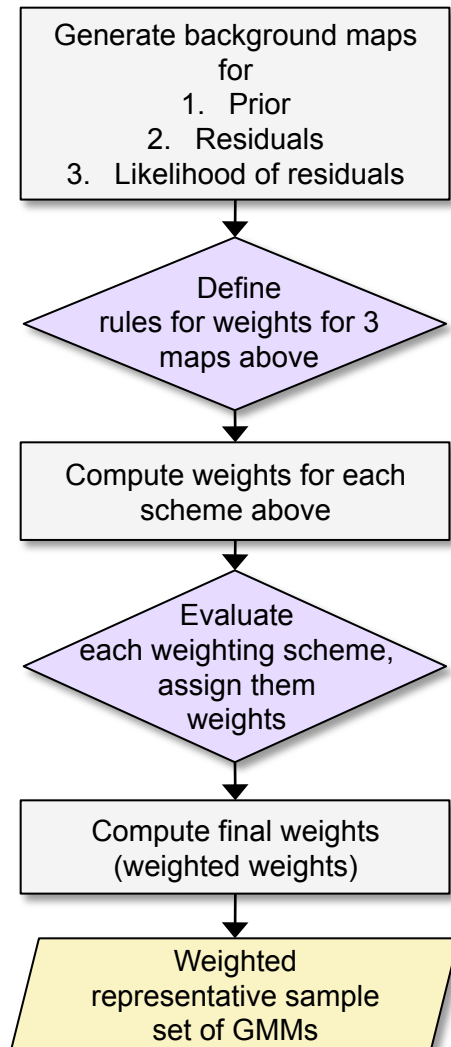
# Median Ground Motions

## 5. Assign weights



# Median Ground Motions

## 5. Assign weights



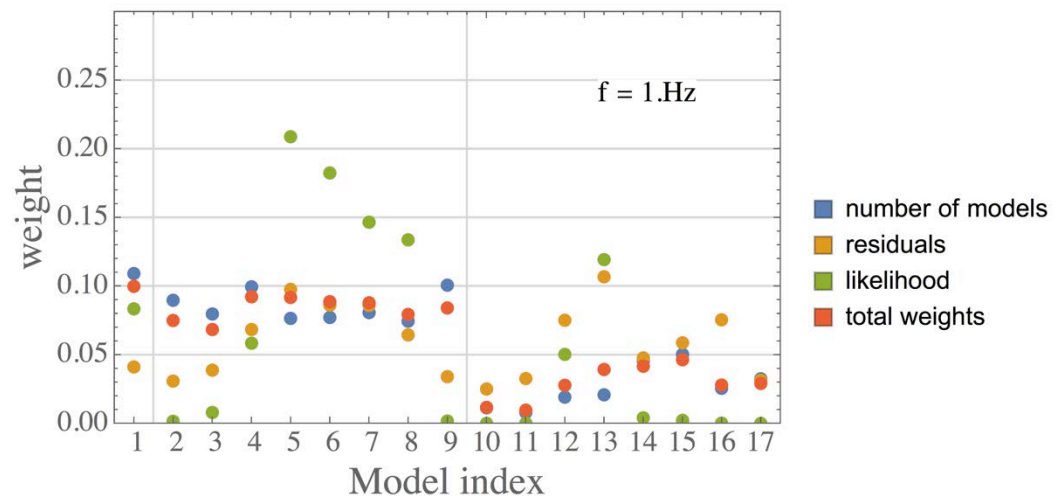
## Final (weights on weights)

Within 1-10 Hz bandwidth:

- 80% for  $w(\text{Nsamples})$
- 10% for  $w(\text{res})$
- 10% for  $w(\text{like})$

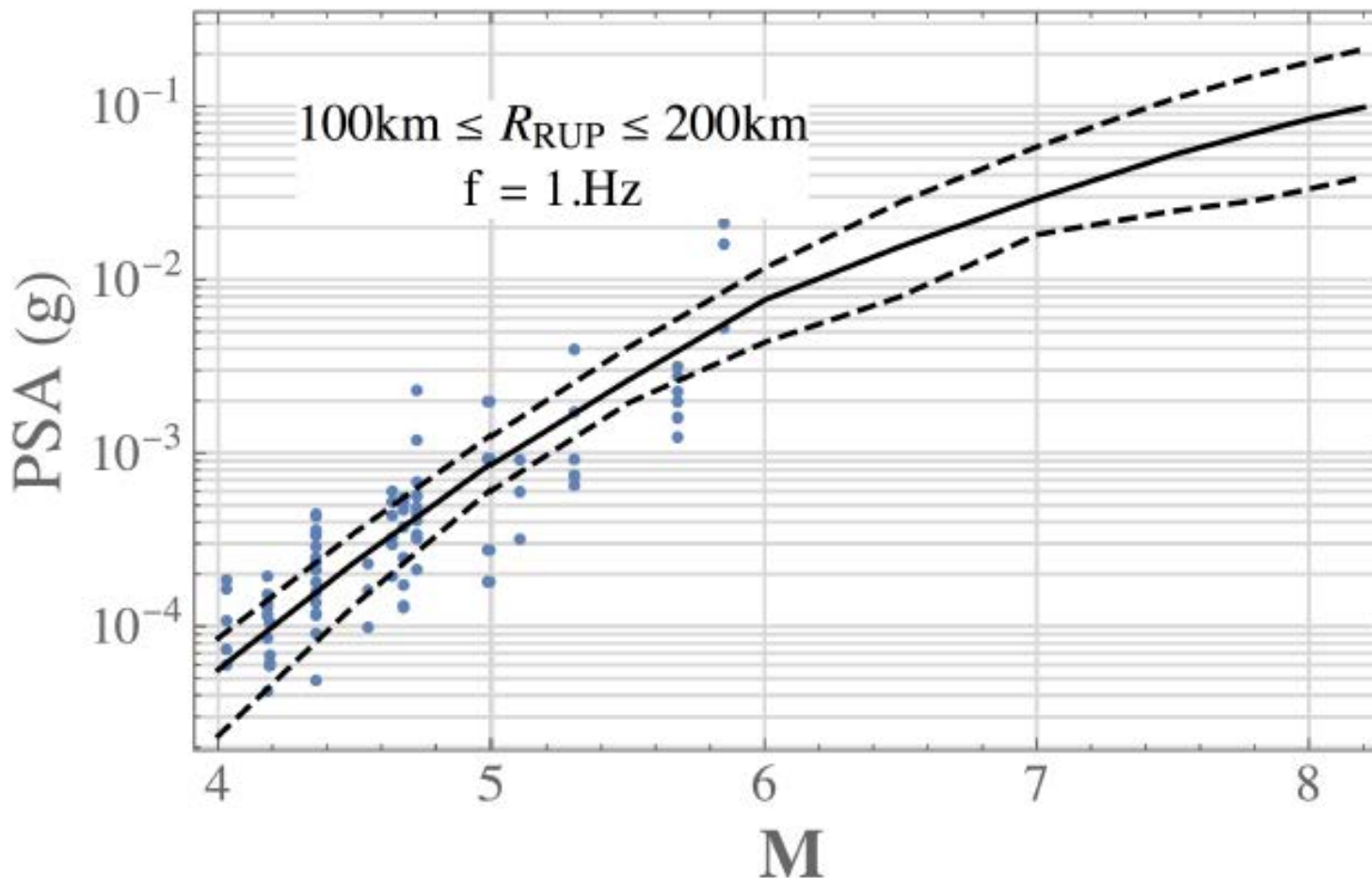
Everywhere else:

- 100% to  $w(\text{NSamples})$



# Sample result

- Scaling of 10<sup>th</sup>, 50<sup>th</sup>, and 90<sup>th</sup> fractiles of final GMM distribution compared with observations



# Sample result

- Scaling of 10<sup>th</sup>, 50<sup>th</sup>, and 90<sup>th</sup> fractiles of seeds and NGA-East models

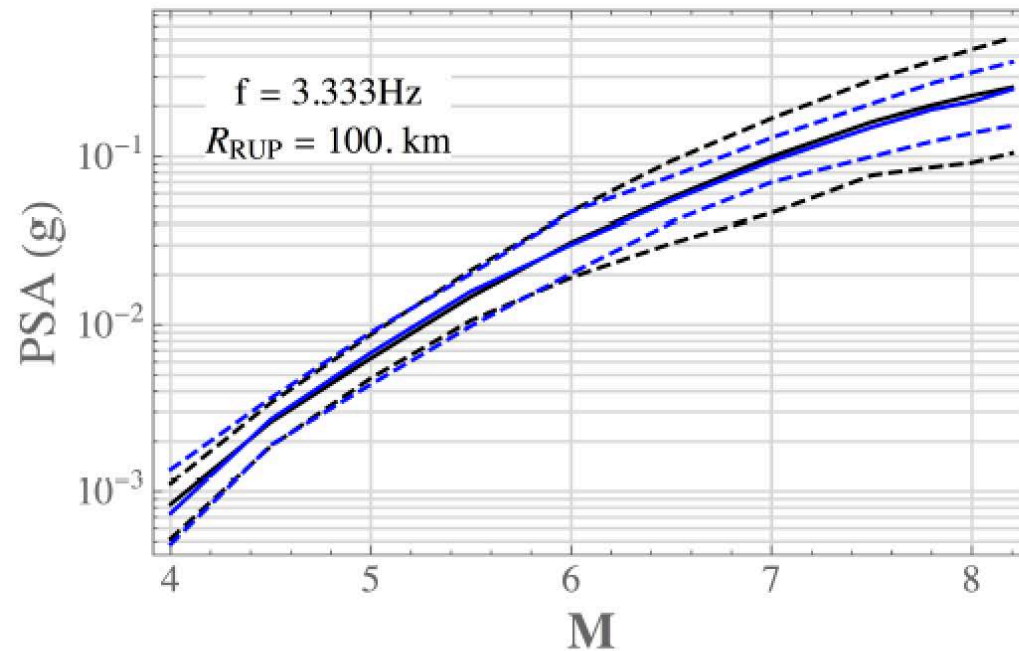


Figure 5182: 10%,50% and 90% fractiles of NGA-East GMMs (black) and seed models (blue), for  $R_{RUP} = 100.$ , and  $f = 3.333\text{Hz}$

# Sample result

- CDF of ground motions

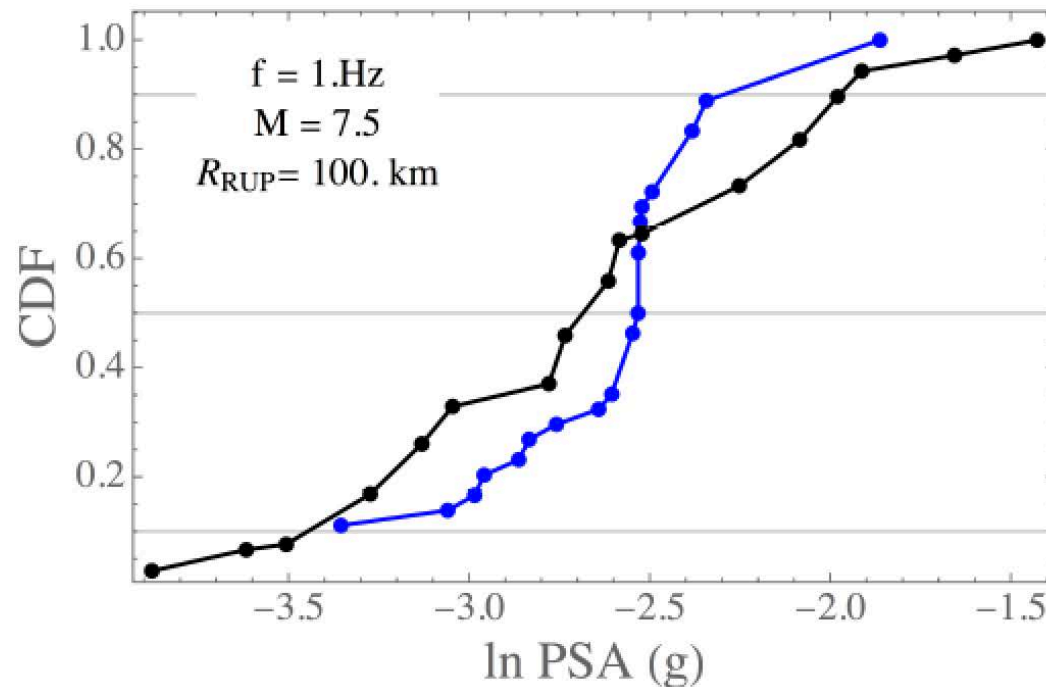


Figure 2355: Cumulative density function of NGA-East GMMs (black) and seed models (blue), for a scenario with  $M = 7.5$ ,  $R_{RUP} = 100.$ , and  $f = 1.Hz$

# Standard deviation

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$$\sigma = \sqrt{\phi_{SS}^2 + \phi_{S2S}^2 + \tau^2}$$

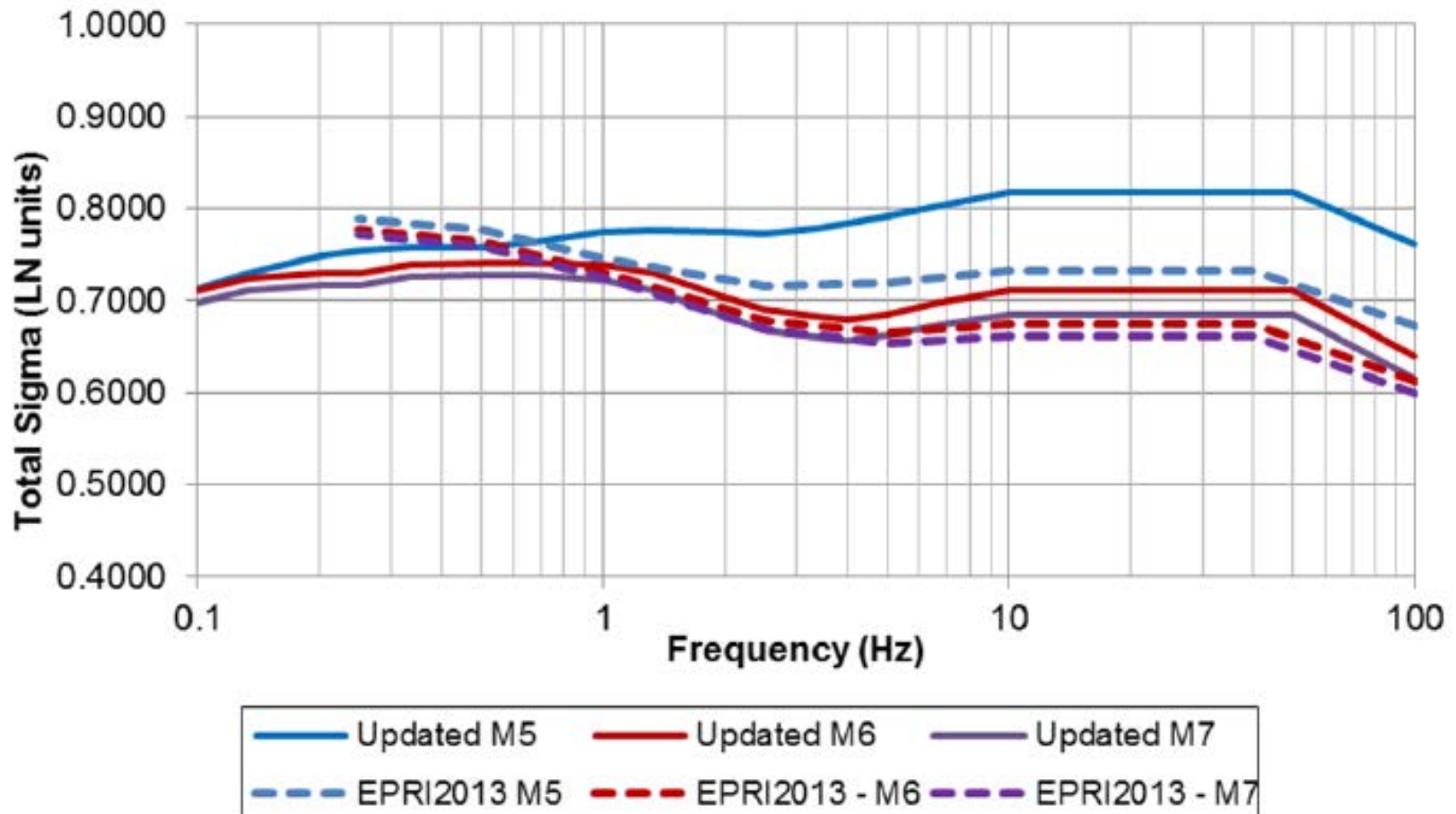
$$\sigma = \sqrt{\phi^2 + \tau^2}$$

- Model developed for partitioned residuals
  - $\phi$ ,  $\phi_{S2S}$ ,  $\phi_{SS}$ ,  $\tau$
- Considered models from data-rich regions (NGA-West2, Japan) to extrapolate models to larger magnitude
- $\phi_{S2S}$  also from NGA-East database
- Evaluated the models and assigned weights
- For USGS application, favored NGA-West2 based model (updated EPRI 2013)



# Recommended Sigma model

Based on final NGA-West2 models and updated relative to EPRI 2013.



# GMC model summary

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Median GMM logic tree applicable to CENA, **M**4-8.2,  $R_{RUP}$  up to 1,500 km

- CBR of the TDI in medians: 17 GMMs per frequency, provided in tables of **M**, R (no equations) for each PSA frequency, PGA and PGV
- The following models provided as “adjustments” to the 17 median GMMs
  - Source-depth adjustment factors that interface with CEUS SSC
  - Gulf Coast region adjustments

Use recommended ergodic sigma model for USGS applications

# Thank you...

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